CAT93HC46

1K-Bit High Speed Microwire Serial EEPROM

FEATURES

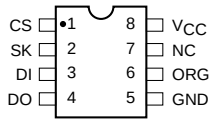
- **High speed operation:**
  - **93HC46: 3MHz**
- **Low power CMOS technology**
- **1.8 to 6.0 volt operation**
- **Selectable x8 or x16 memory organization**
- **Self-timed write cycle with auto-clear**
- **Sequential Read**
- **Software write protection**
- **Power-up inadvertent write protection**
- **1,000,000 program/erase cycles**
- **100 year data retention**
- **Commercial, industrial and automotive temperature ranges**

DESCRIPTION

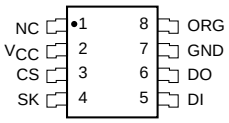
The CAT93HC46 is a 1K-bit Serial EEPROM memory devices which is configured as either registers of 16 bits (ORG pin at V_{CC}) or 8 bits (ORG pin at GND). Each register can be written (or read) serially by using the DI (or DO) pin. The CAT93HC46 is manufactured using Catalyst's advanced CMOS EEPROM floating gate technology. The device is designed to endure 1,000,000 program/erase cycles and has a data retention of 100 years. The CAT93HC46 is available in 8-pin DIP, 8-pin SOIC or 8-pin TSSOP packages.

PIN CONFIGURATION

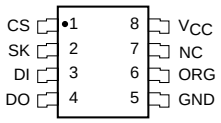
DIP Package (P)



SOIC Package (J)



SOIC Package (S)



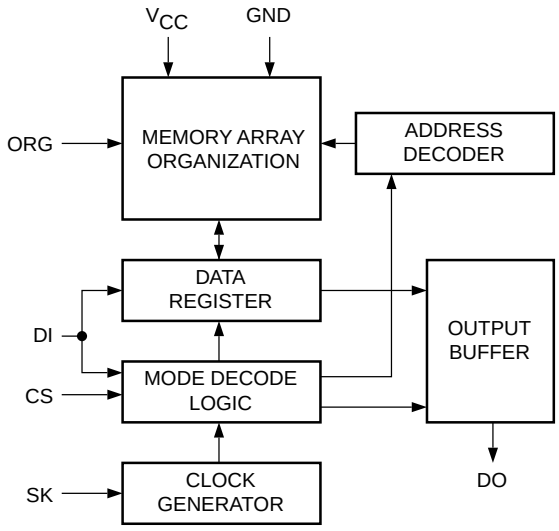
TSSOP Package (U)

PIN FUNCTIONS

Pin Name	Function
CS	Chip Select
SK	Clock Input
DI	Serial Data Input
DO	Serial Data Output
V_{CC}	+1.8 to 6.0V Power Supply
GND	Ground
ORG	Memory Organization
NC	No Connection
PE*	Program Enable

Note: When the ORG pin is connected to VCC, the X16 organization is selected. When it is connected to ground, the X8 pin is selected. If the ORG pin is left unconnected, then an internal pullup device will select the X16 organization.

BLOCK DIAGRAM



ABSOLUTE MAXIMUM RATINGS*

Temperature Under Bias ..... –55°C to +125°C

Storage Temperature ..... –65°C to +150°C

Voltage on any Pin with Respect to Ground(1) ..... –2.0V to +V_{CC} +2.0V

V_{CC} with Respect to Ground ..... –2.0V to +7.0V

Package Power Dissipation Capability (T_A = 25°C) 1.0W

Lead Soldering Temperature (10 secs) ..... 300°C

Output Short Circuit Current(2) ..... 100 mA

*COMMENT

Stresses above those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions outside of those listed in the operational sections of this specification is not implied. Exposure to any absolute maximum rating for extended periods may affect device performance and reliability.

RELIABILITY CHARACTERISTICS

Symbol	Parameter	Min.	Max.	Units	Reference Test Method
N_{END}(3)	Endurance	1,000,000		Cycles/Byte	MIL-STD-883, Test Method 1033
T_{DR}(3)	Data Retention	100		Years	MIL-STD-883, Test Method 1008
V_{ZAP}(3)	ESD Susceptibility	2000		Volts	MIL-STD-883, Test Method 3015
I_{LTH}(3)(4)	Latch-Up	100		mA	JEDEC Standard 17

D.C. OPERATING CHARACTERISTICS

(Over recommended operating conditions, unless otherwise specified.)

Symbol	Parameter	Limits			Units	Test Conditions
		Min.	Typ.	Max.		
I_{CC1}	Power Supply Current (Operating Write)			3	mA	f_{SK} = 3MHz V_{CC} = 5.0V
I_{CC2}	Power Supply Current (Operating Read)			500	µA	f_{SK} = 3MHz V_{CC} = 5.0V
I_{SB1}	Power Supply Current (Standby) (x8 Mode)			10	µA	CS = 0V ORG=GND
I_{SB2}(5)	Power Supply Current (Standby) (x16Mode)			0	µA	CS=0V ORG=Float or V_{CC}
I_{LI}	Input Leakage Current (Including ORG pin)			1	µA	V_{IN} = 0V to V_{CC}
I_{LO}	Output Leakage Current (Including ORG pin)			1	µA	V_{OUT} = 0V to V_{CC}, CS = 0V
V_{IL1}	Input Low Voltage	-0.1		0.8	V	4.5V ≤ V_{CC} < 5.5V
V_{IH1}	Input High Voltage	2		V_{CC} + 1	V	4.5V ≤ V_{CC} < 5.5V
V_{IL2}	Input Low Voltage	0		V_{CC} x 0.2	V	1.8V ≤ V_{CC} < 4.5V
V_{IH2}	Input High Voltage	V_{CC} x 0.7		V_{CC} + 1	V	1.8V ≤ V_{CC} < 4.5V
V_{OL1}	Output Low Voltage			0.4	V	4.5V ≤ V_{CC} < 5.5V, I_{OL}=2.1mA
V_{OH1}	Output High Voltage	2.4			V	4.5V ≤ V_{CC} < 5.5V, I_{OH} = -400mA
V_{OL2}	Output Low Voltage			0.2	V	1.8V ≤ V_{CC} < 4.5V, I_{OL}=1mA
V_{OH2}	Output High Voltage	V_{CC}-0.2				1.8V ≤ V_{CC} < 4.5V, I_{OH} = -100µA

Note:
(1) The minimum DC input voltage is –0.5V. During transitions, inputs may undershoot to –2.0V for periods of less than 20 ns. Maximum DC voltage on output pins is V_{CC} +0.5V, which may overshoot to V_{CC} +2.0V for periods of less than 20 ns.
(2) Output shorted for no more than one second. No more than one output shorted at a time.
(3) This parameter is tested initially and after a design or process change that affects the parameter.
(4) Latch-up protection is provided for stresses up to 100 mA on address and data pins from –1V to V_{CC} +1V.
(5) Standby Current (ISB_2)=0µA (<900nA).

RECOMMENDED OPERATING CONDITIONS

Temperature	Minimum	Maximum
Commercial	0˚C	+70˚C
Industrial	-40˚C	+85˚C
Automotive	-40˚C	+105˚C
Extended	-40˚C	+125˚C

Device	Supply Voltage Range
CAT93HC46	2.5V to 6.0V
CAT93HC46-1.8	1.8V to 6.0V

PIN CAPACITANCE

Symbol	Test	Max.	Units	Conditions
C_{OUT}(1)	OUTPUT CAPACITANCE (DO)	5	pF	V_{OUT}=0V, T_A=25˚C, f_{SK}=1MHz
C_{IN}(1)	INPUT CAPACITANCE (CS, SK, DI, ORG)	5	pF	V_{IN}=0V, T_A=25˚C, f_{SK}=1MHz

INSTRUCTION SET

Instruction	Start Bit	Opcode	Address		Data		Comments
			x8	x16	x8	x16	
READ	1	10	A6-A0	A5-A0			Read Address AN–A0
ERASE	1	11	A6-A0	A5-A0			Clear Address AN–A0
WRITE	1	01	A6-A0	A5-A0	D7-D0	D15-D0	Write Address AN–A0
EWEN	1	00	11XXXXX	11XXXX			Write Enable
EWDS	1	00	00XXXXX	00XXXX			Write Disable
ERAL	1	00	10XXXXX	10XXXX			Clear All Addresses
WRAL	1	00	01XXXXX	01XXXX	D7-D0	D15-D0	Write All Addresses

Note:
(1) This parameter is tested initially and after a design or process change that affects the parameter.

POWER-UP TIMING (1)(2)

SYMBOL	PARAMETER	Max	Units
t_{PUR}	Power-up to Read Operation	1	ms
t_{PUW}	Power-up to Write Operation	1	ms

A.C. CHARACTERISTICS

		Limits							
		V_{CC} = 1.8V-6V		V_{CC} = 2.5V-6V		V_{CC} = 4.5V-5.5V			
SYMBOL	PARAMETER	Min.	Max.	Min.	Max.	Min.	Max.	UNITS	
t_{CSS}	CS Setup Time	200		100		50		ns	
t_{CSH}	CS Hold Time	0		0		0		ns	
t_{DIS}	DI Setup Time	400		200		50		ns	
t_{DIH}	DI Hold Time	400		200		50		ns	
t_{PD1}	Output Delay to 1		1		0.5		0.1	µs	C_L = 100pF (3)
t_{PD0}	Output Delay to 0		1		0.5		0.1	µs	
t_{HZ}(1)	Output Delay to High-Z		400		200		100	ns	
t_{EW}	Program/Erase Pulse Width		5		5		5	ms	
t_{CSMIN}	Minimum CS Low Time	1		0.5		0.1		µs	
t_{SKHI}	Minimum SK High Time	1		0.5		0.1		µs	
t_{SKLOW}	Minimum SK Low Time	1		0.5		0.1		µs	
t_{SV}	Output Delay to Status Valid		1		0.5		0.1	µs	
SK_{MAX}	Maximum Clock Frequency	DC	250	DC	1000	DC	3000	kHz	

NOTE:
(1) This parameter is tested initially and after a design or process change that affects the parameter.
(2) t_{PUR} and t_{PUW} are the delays required from the time V_{CC} is stable until the specified operation can be initiated.
(3) The input levels and timing reference points are shown in “AC Test Conditions” table.

A.C. TEST CONDITIONS

Input Rise and Fall Times	≤ 50ns	
Input Pulse Voltages	0.4V to 2.4V	4.5V ≤ V_{CC} ≤ 5.5V
Timing Reference Voltages	0.8V, 2.0V	4.5V ≤ V_{CC} ≤ 5.5V
Input Pulse Voltages	0.2V_{CC} to 0.7V_{CC}	1.8V ≤ V_{CC} ≤ 4.5V
Timing Reference Voltages	0.5V_{CC}	1.8V ≤ V_{CC} ≤ 4.5V

DEVICE OPERATION

The CAT93HC46 is a 1024-bit nonvolatile memory intended for use with industry standard microprocessors. The CAT93HC46 can be organized as either registers of 16 bits or 8 bits. When organized as X16, seven 9-bit instructions control the reading, writing and erase operations of the device. When organized as X8, seven 10-bit instructions control the reading, writing and erase operations of the device. The CAT93HC46 operates on a single power supply and will generate on chip, the high voltage required during any write operation.

Instructions, addresses, and write data are clocked into the DI pin on the rising edge of the clock (SK). The DO pin is normally in a high impedance state except when reading data from the device, or when checking the ready/busy status after a write operation.

The ready/busy status can be determined after the start of a write operation by selecting the device (CS high) and polling the DO pin; DO low indicates that the write operation is not completed, while DO high indicates that the device is ready for the next instruction. If necessary, the DO pin may be placed back into a high impedance state during chip select by shifting a dummy “1” into the DI pin. The DO pin will enter the high impedance state on the falling edge of the clock (SK). Placing the DO pin into the high impedance state is recommended in applications where the DI pin and the DO pin are to be tied together to form a common DI/O pin.

Figure 1. Sychronous Data Timing

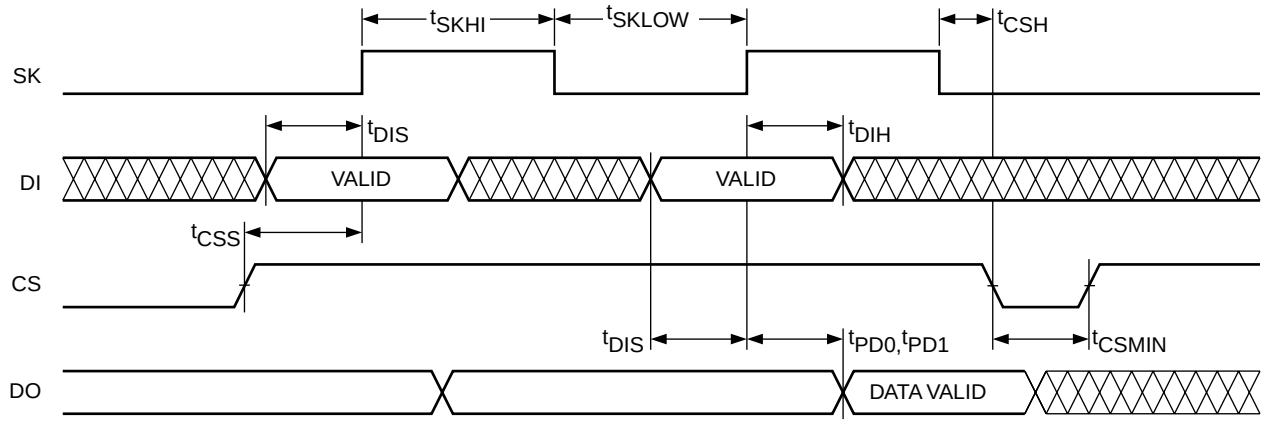
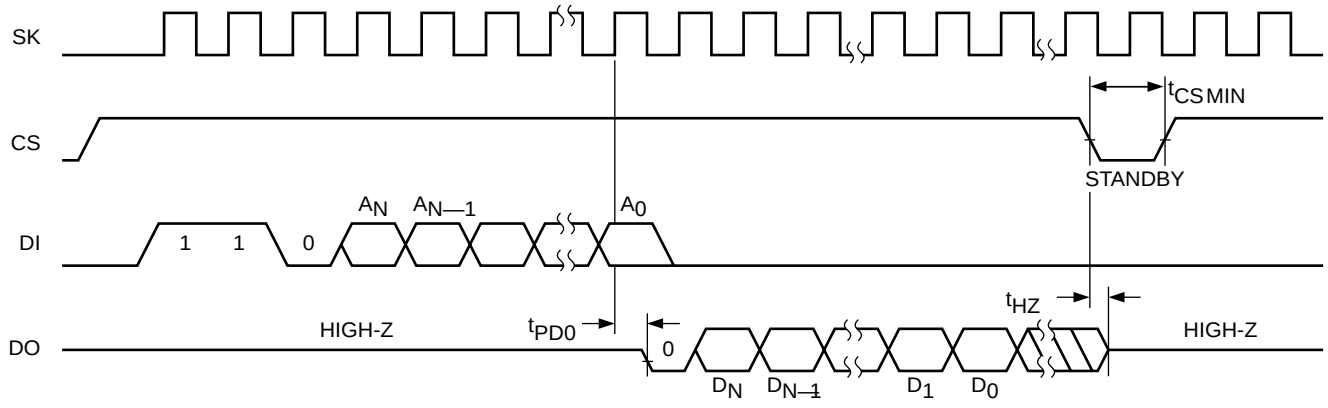


Figure 2a. Read Instruction Timing



The format for all instructions sent to the device is a logical "1" start bit, a 2-bit (or 4-bit) opcode, 6-bit byte/word address (an additional bit when organized X8) and for write operations a 16-bit data field (8-bit for X8 organizations).

Read

Upon receiving a READ command and an address (clocked into the DI pin), the DO pin of the CAT93HC46 will come out of the high impedance state and, after sending an initial dummy zero bit, will begin shifting out the data addressed (MSB first). The output data bits will toggle on the rising edge of the SK clock and are stable after the specified time delay (t_{PD0} or t_{PD1})

After the initial data word has been shifted out and CS remains asserted with the SK clock continuing to toggle, the CAT93HC46 will automatically increment to the next address and shift out the next data word in a sequential READ mode. As long as CS is continuously asserted and SK continues to toggle, the device will keep incrementing to the next address automatically until it reaches to the end of the address space, then loops back to address 0. In the sequential READ mode, only the initial data word is preceeded by a dummy zero bit. All subsequent data words will follow without a dummy zero bit.

Write

After receiving a WRITE command, address and the data, the CS (Chip Select) pin must be deselected for a minimum of t_{CSMIN}. The falling edge of CS will start the self clocking clear and data store cycle of the memory location specified in the instruction. The clocking of the SK pin is not necessary after the device has entered the self clocking mode. (Note 1.) The ready/busy status of the CAT93HC46 can be determined by selecting the device and polling the DO pin. Since this device features Auto-Clear before write, it is NOT necessary to erase a memory location before it is written into.

Erase

Upon receiving an ERASE command and address, the CS (Chip Select) pin must be deasserted for a minimum of t_{CSMIN}. The falling edge of CS will start the self clocking

Figure 2b. Sequential Read Instruction Timing

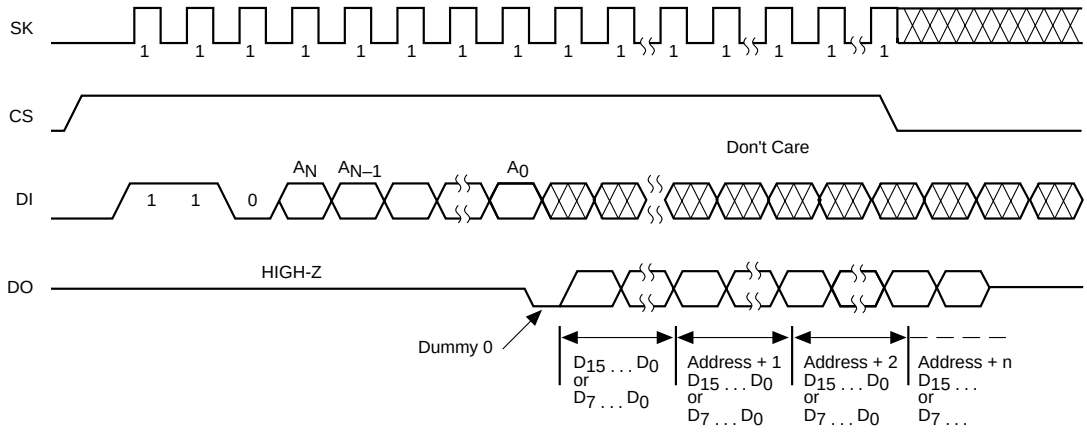
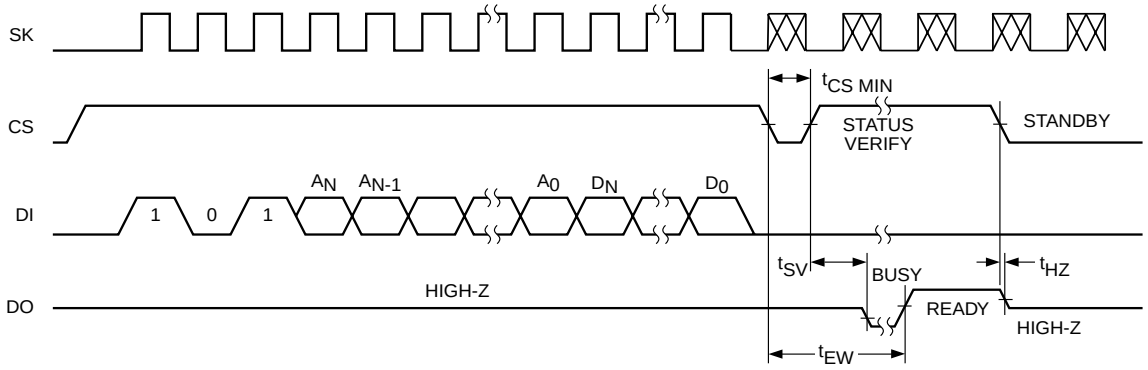


Figure 3. Write Instruction Timing



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clear cycle of the selected memory location. The clocking of the SK pin is not necessary after the device has entered the self clocking mode. (Note 1.) The ready/busy status of the CAT93HC46 can be determined by selecting the device and polling the DO pin. Once cleared, the content of a cleared location returns to a logical "1" state.

Erase/Write Enable and Disable

The CAT93HC46 powers up in the write disable state. Any writing after power-up or after an EWDS (write disable) instruction must first be preceded by the EWEN (write enable) instruction. Once the write instruction is enabled, it will remain enabled until power to the device is removed, or the EWDS instruction is sent. The EWDS instruction can be used to disable all CAT93HC46 write and clear instructions, and will prevent any accidental writing or clearing of the device. Data can be read normally from the device regardless of the write enable/disable status.

Erase All

Upon receiving an ERAL command, the CS (Chip Select) pin must be deselected for a minimum of t_{CSMIN}. The falling edge of CS will start the self clocking clear cycle of all memory locations in the device. The clocking of the SK pin is not necessary after the device has entered the self clocking mode. (Note 1.) The ready/busy status of the CAT93HC46 can be determined by selecting the device and polling the DO pin. Once cleared, the contents of all memory bits return to a logical "1" state.

Write All

Upon receiving a WRAL command and data, the CS (Chip Select) pin must be deselected for a minimum of t_{CSMIN}. The falling edge of CS will start the self clocking data write to all memory locations in the device. The clocking of the SK pin is not necessary after the device has entered the self clocking mode. The ready/busy status of the CAT93HC46 can be determined by selecting the device and polling the DO pin. It is not necessary for all memory locations to be cleared before the WRAL command is executed.

Note 1: After the last data bit has been sampled, Chip Select (CS) must be brought Low before the next rising edge of the clock (SK) in order to start the self-timed high voltage cycle. This is important because if the CS is brought low before or after this specific frame window, the addressed location will not be programmed or erased.

Figure 4. Erase Instruction Timing

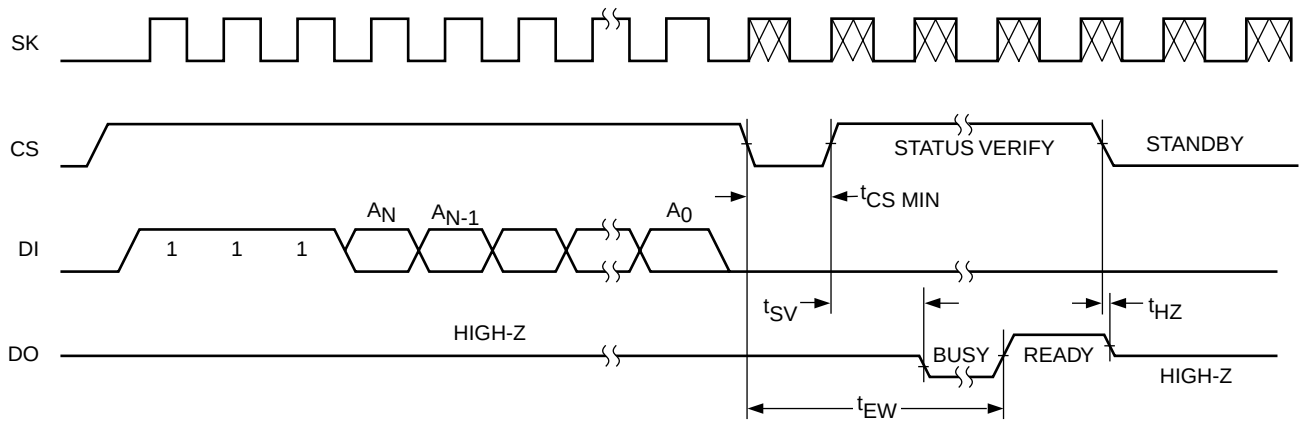


Figure 5. EWEN/EWDS Instruction Timing

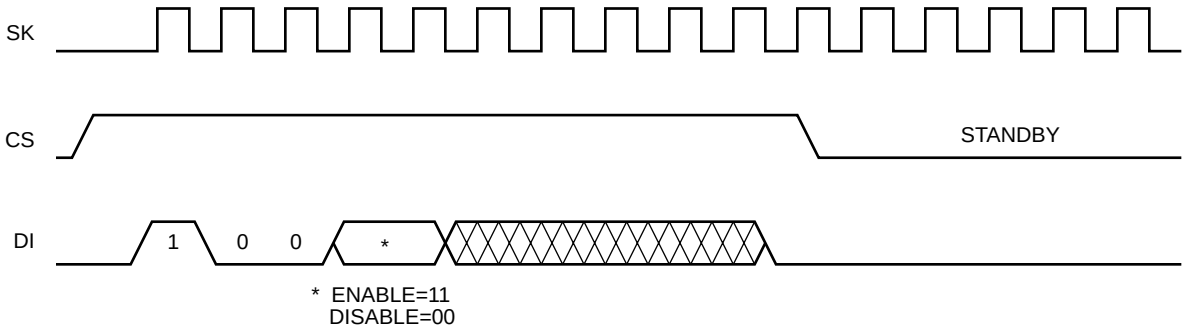


Figure 6. ERAL Instruction Timing

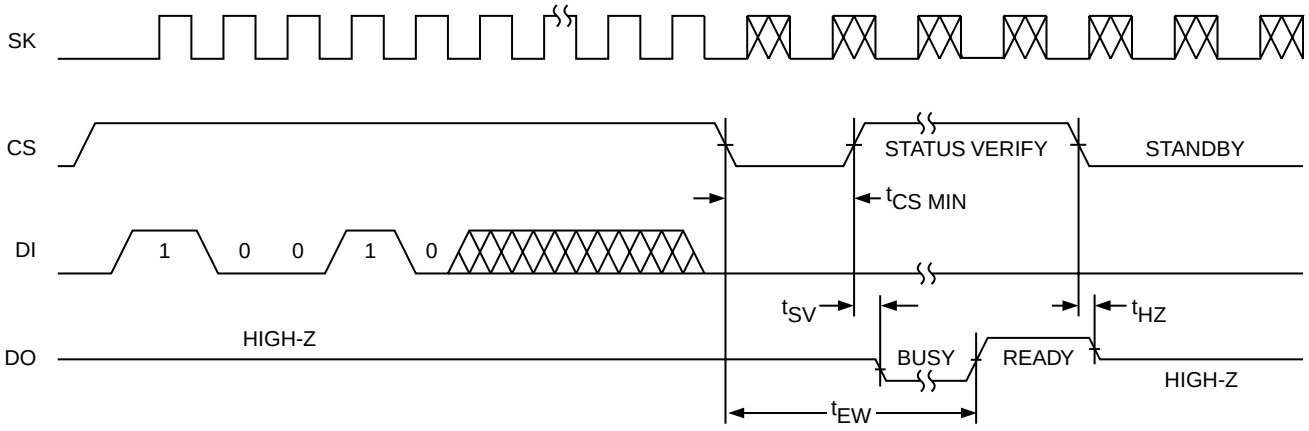
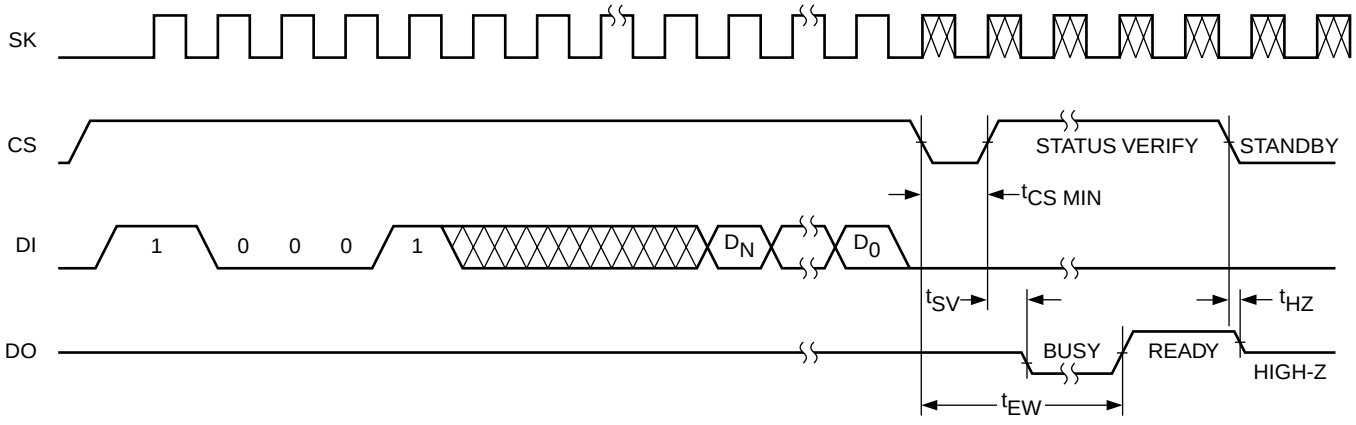
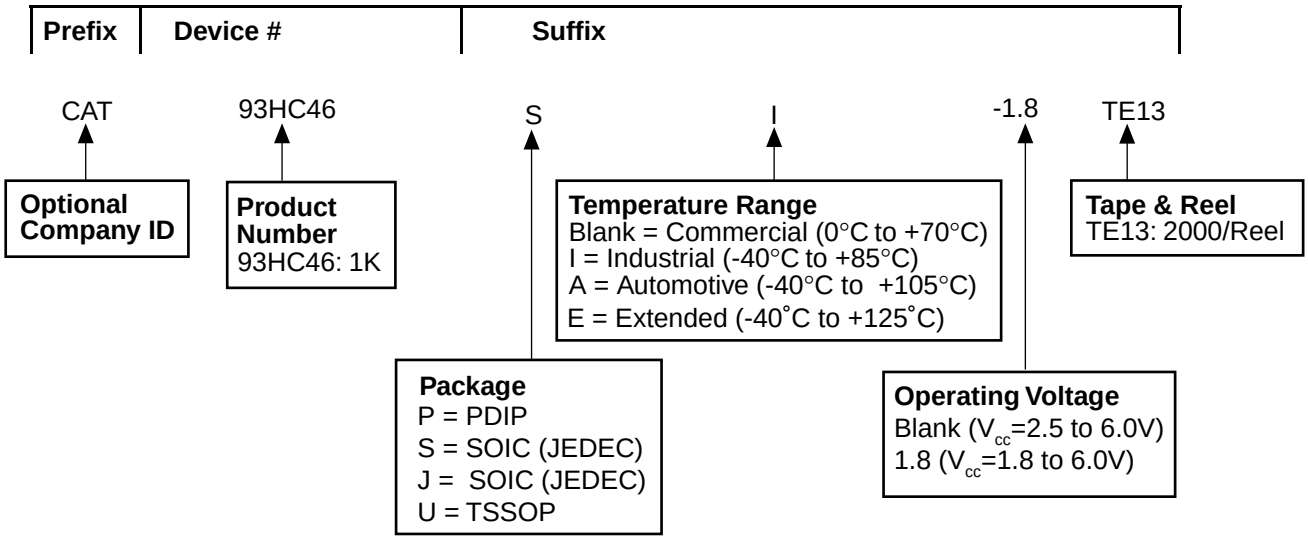


Figure 7. WRAL Instruction Timing



ORDERING INFORMATION



Notes:
(1) The device used in the above example is a 93HC46SI-1.8TE13 (SOIC, Industrial Temperature, 1.8 Volt to 6 Volt Operating Voltage, Tape & Reel)

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